## PREVIEW QUESTION BANK

Module Name : cec24-ma05 Operations Research-ENG Exam Date : 18-May-2024 Batch : 09:00-12:00

Sr. No.	Client Question ID	Question Body and Alternatives	Marks	Negati Mark
bject	ive Question			
	11071001		2.0	0.00
		In combined calluffing of an LDD the cardy advantage desirable and		
		In graphical solution of an LPP, the redundant constraint is one		
		which forms the boundary of the feasible region		
		which does not optimize the objective function		
		which does not optimize the objective function     which does not form boundary of the feasible region		
		which optimizes the objective function		
		A1:1		
		A2:2		
		A2 . 2		
		A3:3		
		A4:4		
signt	ive Question			
njeci	11071002		2.0	0.00
	110/1002	If at least one basic variable is zero in a basic feasible solution (BFS) of an LPP then	2.0	0.00
		it is called		
		TO GATING		
		1. degenerate		
		2. non-degenerate		
		3. infeasible		
		4. unbounded		
		4. unbounded		
		A1:1		
		A2:2		
		A3:3		
		A4:4		
bject	ive Question			
	11071003		2.0	0.00
		If a primal LPP has unbounded solution, then its corresponding dual will have		
		1. unbounded solution		
		2. unique solution		
		3. feasible solution		
				II
		4. no feasible solution		
		4. no feasible solution		
		4. no feasible solution		
		A1:1		

		A2:2		
		A3:3		
		A4:4		
Object:	ive Question 11071004		2.0	0.00
	110/1004	Which of the following statements is/are correct?	2.0	0.00
		Statement 1: If the primal problem is in its standard form, dual variables will be non-negative.		
		Statement 2: Dual simplex method is applicable to an LPP, if initial basic feasible solution is not optimum.		
		Statement 3: Dual simplex method always leads to degenerate basic feasible solution.		
		Statement 4: If the number of primal variables is very small and the number of		
		constraints is very large, then it is more efficient to solve the dual problem rather		
		than the primal problem.		
		1. Statement 1		
		2. Statement 2		
		3. Both Statement 2 and Statement 3		
		4. Statement 4		
		A1:1		
		A2:2		
		A3:3		
		A4:4		
Object	ive Question			
5	11071005	Dual simplex method is applicable to the LPPs that start with	2.0	0.00
		1. an infeasible solution		
		an infeasible but optimum solution		
		3. a feasible solution		
		4. a feasible and optimum solution		
		A1:1		
		A1.1		
		A2:2		
		A3:3		
		A4:4		
	ive Question		2.0	0.00
6	11071006		2.0	0.00

		In a transportation problem, there are five supply and six demand centres. The total quantity of supply available is greater than the total demand. The number of allocations without degeneracy during an iteration is  1. 9 2. 10 3. 11 4. 12  A1:1  A2:2  A3:3  A4:4											
Object	ive Question								0.00				
7	11071007												
Object 8	ive Question 11071008							2.0	0.00				
8	110/1008	Find the ran		alues of p and q v	which will render the	entry (2,2) a saddle		2.0	0.00				
					Player B								
				В <sub>1</sub>	В2	В3							
			A <sub>1</sub>	2	4	5							
		Player A	A <sub>2</sub>	10	7	q							
			A <sub>3</sub>	4	р	6							
		1. $p \ge 5$ , $q \le$ 2. $p \le 7$ , $q \ge$ 3. $p \le 5$ , $q \ge$ 4. $p \ge 7$ , $q \le$	7 5										

		A1:1		
		A2:2		
		A3:3		
		A4:4		
Object	ive Question			
9	11071009		2.0	0.00
		While solving a 2× n game graphically, the extreme point of the envelop		
		considered is		
		1. minimax point		
		maximin point		
		3. either maximin point or minimax point		
		4. neither maximin point nor minimax point		
		A1:1		
		A2:2		
		A3:3		
		A3.3		
		A.A 4		
		A4:4		
	ive Question		2.0	0.00
Objecti 10	11071010	If a job is having minimum processing time under both the machines, then the job is	2.0	0.00
		If a job is having minimum processing time under both the machines, then the job is placed in	2.0	0.00
		placed in	2.0	0.00
		placed in  1. any one (first or last) position	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position  4. both first and last positions	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position  4. both first and last positions  Al: 1	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position  4. both first and last positions	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position  4. both first and last positions  Al: 1	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position  4. both first and last positions  Al: 1	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position  4. both first and last positions  A1:1	2.0	0.00
		placed in  1. any one (first or last) position  2. available last position  3. available first position  4. both first and last positions  A1:1	2.0	0.00
		placed in  1. any one (first or last) position 2. available last position 3. available first position 4. both first and last positions  A1:1  A2:2  A3:3	2.0	0.00
10		placed in  1. any one (first or last) position 2. available last position 3. available first position 4. both first and last positions  A1:1  A2:2  A3:3	2.0	0.00
10	11071010	placed in  1. any one (first or last) position 2. available last position 3. available first position 4. both first and last positions  A1:1  A2:2  A3:3  A4:4	2.0	0.00
Objecti	11071010	placed in  1. any one (first or last) position 2. available last position 3. available first position 4. both first and last positions  A1:1  A2:2  A3:3		
Objecti	11071010	placed in  1. any one (first or last) position 2. available last position 3. available first position 4. both first and last positions  A1:1  A2:2  A3:3  A4:4		
Objecti	11071010	placed in  1. any one (first or last) position 2. available last position 3. available first position 4. both first and last positions  A1:1  A2:2  A3:3  A4:4  In sequencing problems, the assumption of 'no passing rule' means.		
Objecti	11071010	placed in  1. any one (first or last) position 2. available last position 3. available first position 4. both first and last positions  A1:1  A2:2  A3:3  A4:4  In sequencing problems, the assumption of 'no passing rule' means:  1. A job once loaded on a machine should not be removed until it is completed. 2. A job cannot be processed on the second machine unless it is processed on the first machine.		
Objecti	11071010	placed in  1. any one (first or last) position 2. available last position 3. available first position 4. both first and last positions  A1:1  A2:2  A3:3  A4:4  In sequencing problems, the assumption of 'no passing rule' means:  1. A job once loaded on a machine should not be removed until it is completed.  2. A job cannot be processed on the second machine unless it is processed on the first machine.  3. A machine should not be started unless the other is ready to start.		
Objecti	11071010	placed in  1. any one (first or last) position 2. available last position 3. available first position 4. both first and last positions  A1:1  A2:2  A3:3  A4:4  In sequencing problems, the assumption of 'no passing rule' means:  1. A job once loaded on a machine should not be removed until it is completed. 2. A job cannot be processed on the second machine unless it is processed on the first machine.		

			A1:1		
			A2:2		
			A3:3		
			A4:4		
ŀ					
		ve Question		2.0	0.00
	12	110/1012	In retrogressive failures, the failure probability ——with time.	2.0	0.00
			1. increases		
			2. decreases		
			3. may increase or decrease		
			4. remains constant		
			A1:1		
			A2:2		
			A3:3		
			A4:4		
		ve Question			
	13	11071013	When money value changes with time at 20%, the discount factor for second year is	2.0	0.00
			1.1		
			2.0		
			3. 0.833 4. 0.6955		
			4. 0.0933		
			A1:1		
			42.2		
			A2:2		
			A2 . 2		
			A3:3		
			A4:4		
			A4.4		
	Objecti	ve Question			
		11071014		2.0	0.00
			Economic Order Quantity is given by: (where, $c_1$ = inventory carrying cost, $c_3$ = ordering cost, $R$ = demand rate for the product)		
			1. (2c <sub>1</sub> /c <sub>3</sub> ) <sup>1/2</sup>		
			2. (2c <sub>3</sub> /(c <sub>1</sub> R)) <sup>1/2</sup>		
			3. 2c <sub>3</sub> R/c <sub>1</sub> 4. (2c <sub>3</sub> R/c <sub>1</sub> ) <sup>1/2</sup>		
			4. (ZU3NVU1) -		

		A1:1		
		A2:2		
		A3:3		
		A4:4		
Object	ive Question			
	11071015		2.0	0.00
		The lead-time is		
		1. the time to place orders for materials		
		2. the time of receiving materials		
		<ul><li>3. the time between receipt of material and using materials</li><li>4. the time between placing the order and receiving the materials</li></ul>		
		4. the time between placing the order and receiving the materials		
		A1:1		
		A2:2		
		A2:2		
		A3:3		
		A3 . 3		
		A4:4		
		A7.7		
Object	ive Question			
16	11071016		2.0	0.00
		Newsboy model is		
		1. deterministic model		
		2. single-period model		
		multi-period model     single or multi-period model		
		4. Single of multi-period model		
		A1 1		
		A1:1		
		A2:2		
		A2 . 2		
		A3:3		
		1.5		
		A4:4		
Object	ive Question			
17	11071017		2.0	0.00
		In (M/M/1) : (∞/FIFO) model, 1/(μ – λ) represents		
		expected number of units in the system		
		expected length of the queue     expected waiting time in the queue		
		expected waiting time in the queue     expected waiting time in the system		
		Siposios maining and in the operation		
		A1.1		
		A1:1		

		A2:2		
		A3:3		
		A4:4		
Object	ive Question			I
18	11071018	Customers arrive at a reception counter at an average interval rate of 10 minutes and the receptionist takes an average of 6 minutes for one customer. Then the average queue length is  1. 7/10 2. 9/10 3. 11/10 4. 3/10	2.0	0.00
		A1:1 A2:2		
		A3:3 A4:4		
Object	ive Question			
19	11071019	If for a period of 2 hours in a day (8-10 AM) trains arrive at the yard every 20 minutes, but the service time remains 36 minutes, then the probability that the yard is empty is  1. 0.02 2. 0.04 3. 0.06 4. 0.08  A1:1  A2:2  A3:3  A4:4	2.0	0.00
20	11071020		2.0	0.00
		Commonly assumed probability distribution(s) of service pattern is/are  1. Poisson distribution 2. Exponential distribution 3. Erlang distribution 4. Exponential distribution and Erlang distribution		
	1		1	II .

		A1:1		
		A2:2		
		A3:3		
		A4:4		
Objecti	ive Question			
	11071021	The activity which does not consume neither any resource nor time is known as	2.0	0.00
		Null activity     Dummy activity     Predecessor activity		
		4. Special activity		
		A1:1		
		A2:2		
		A3:3		
		A4:4		
Objecti	ive Question			
22	11071022	Given below are two statements:	2.0	0.00
		Statement (I): The critical path in CPM represents the shortest path in a project network.		
		Statement (II): Activities on the critical path have zero slack time.		
		In light of the above statements, choose the <i>most appropriate</i> answer from the options given below.		
		Both Statement (I) and Statement (II) are true.     Both Statement (I) and Statement (II) are false.		
		3. Statement (I) is true, but Statement (II) is false.  4. Statement (I) is false, but Statement (II) is true.		
		A1:1		
		A2:2		
		A3:3		
		A4:4		
	ive Question			
23	11071023		2.0	0.00

What is the PERT time (T <sub>e</sub> ) with optimistic, most likely a estimations of 6, 10 and 14 days, respectively?  1. 5 2. 7 3. 10 4. 12  A1:1  A2:2  A3:3  A4:4	and pessimistic time		
Objective Question	2	2.0	0.00
In the time-cost optimization using CPM, the crashing of critical path is done starting with the activity having  1. least time slope 2. highest cost slope 3. least cost slope 4. highest time slope  A1:1  A2:2  A3:3  A4:4	f the activities along the	2.0	0.00
The technique of Dynamic Programming was developed  1. Taylor 2. Gilberth 3. Richard Bellman 4. Bellman and Clarke  A1:1  A2:2  A3:3  A4:4  Objective Question	d by	2.0	0.00

26	11071026	7000 45 NF 07 07 0 1 40 NBC 1150 NBCC 1150 NBC	2.0	0.00
		Dynamic programming is a technique used to solve problems by breaking them into		
		smaller overlapping sub-problems and solving them ——		
		1. recursively		
		2. iteratively		
		3. randomly		
		4. concurrently		
		A1:1		
		A2:2		
		42.2		
		A3:3		
		A4:4		
Object	ive Question			
27	11071027		2.0	0.00
21	110/102/	In cutting plane algorithm, each cut involves the introduction of	2.0	0.00
		1. an equality constraint		
		2. less than or equal to constraint		
		3. greater than or equal to constraint		
		4. an artificial variable		
		A1:1		
		A2:2		
		A3:3		
		A4:4		
	ive Question 11071028		2.0	0.00
28	110/1028	Quadratic programming is concerned with the NLPP of optimizing the quadratic	2.0	0.00
		objective function, subject to		
		objective function, subject to		
		linear inequality constraints		
		non-linear inequality constraints		
		3. non-linear equality constraints		
		4. no constraint		
		1. 10 constant		
		A1:1		
		42.2		
		A2:2		
		A3:3		
		A4:4		
		АТ. Т		
	ive Question			
29	11071029		2.0	0.00

		Which of the following methods of solving a Quadratic Programming Problem (QPP) is based on modified simplex method?  1. Wolfe's method 2. Beale's method 3. Fletcher's method 4. Frank-Wolfe method  A1:1  A2:2  A3:3  A4:4		
Object	ive Question			
30	11071030	In each iteration in Beale's method, the objective function is expressed in terms of  1. slack variables 2. surplus variables 3. basic variables 4. non-basic variables  A1:1  A2:2  A3:3  A4:4	2.0	0.00
	ive Question			
31	11071031	By graphical method, it can be shown that the LPP: Max $z = x_1 + x_2$ , subject to $x_1 - x_2 \ge 0$ , $3x_1 - x_2 \le -3$ has  1. unique solution 2. unbounded solution 3. alternative solution 4. no feasible solution  A1:1  A2:2  A3:3	2.0	0.00
Objecti	ive Question			

32	11071032	The set  1. conve  2. not co  3. conce  4. not co  A1:1  A2:2  A3:3	ex onvex ave	, x <sub>2</sub> ): x <sub>1</sub>	x <sub>2</sub> ≤ 1,	$x_1 \ge 0$ ,	$x_2 \ge 0$ } is						2.0	0.00
Ohiaat	i Oti													
33	ive Question												2.0	0.00
	110/1000							simplex meth	nod is giv	en belo	w (x <sub>3</sub> , x <sub>4</sub> ,			
		x <sub>5</sub> are s	lack/sur	plus var	riables	, x <sub>6</sub> artif	icial variab	le) :						
					Cj	3	-1	0	0	0	-M			
		CB	В	ХB	b	a <sub>1</sub>	a <sub>2</sub>	a <sub>3</sub>	a <sub>4</sub>	a <sub>5</sub>	a <sub>6</sub>			
		3	a <sub>1</sub>	Х1	1	1	1/2	-1/2	0	0	x			
			a <sub>4</sub>	Х4	2	0	5/2	1/2	1	0	X			
			a <sub>5</sub>	X <sub>5</sub>	4	0	1	0	0	1	x			
Okiast	in Question	Comple  1. x <sub>1</sub> = 2 2. x <sub>1</sub> = 3 3. x <sub>1</sub> = 3 4. x <sub>1</sub> = 2  A1:1  A2:2  A3:3  A4:4	$x_2, x_2 = 1$ $x_3, x_2 = 0$ $x_4, x_2 = 0$	table ar	nd prod	ceeding	further, the	e optimal sol	ution car	n be obta	ained as			
	ive Question													
34	11071034												2.0	0.00

An intermediate incomplete table of an LPP by simplex method is given below ( $x_4$ ,  $x_5$  are slack variables) :

			Cj	30	23	29	0	0
СВ	В	x <sub>B</sub>	b	a <sub>1</sub>	a <sub>2</sub>	a <sub>3</sub>	a <sub>4</sub>	a <sub>5</sub>
	a <sub>4</sub>	х4	17/2	-4	0	-19/2	1	-5/2
	a <sub>2</sub>	х2	7/2	2	1	5/2	0	1/2

From the final table, the solution of the dual can be obtained as

- 1.  $w_1 = 17/2$ ,  $w_2 = 7/2$
- 2.  $w_1 = 17/2$ ,  $w_2 = 0$
- 3.  $w_1 = 7/2$ ,  $w_2 = 17/2$
- 4.  $w_1 = 0$ ,  $w_2 = 23/2$
- A1:1
- A2:2
- A3:3
- A4:4

Objective Question

35 11071035

An intermediate incomplete table of an LPP by dual simplex method is given below:

	50. 20		c <sub>j</sub>	-2	0	-1	0	0
СВ	В	x <sub>B</sub>	b	a <sub>1</sub>	a <sub>2</sub>	a <sub>3</sub>	a <sub>4</sub>	a <sub>5</sub>
	a <sub>4</sub>	Х4	-7	-5/4	-1/2	0	1	1/4
	a <sub>3</sub>	Х3	2	1/4	-1/2	1	0	-1/4
		Zj - C	j					

Determine the vector which will enter in the basis.

- 1. a<sub>1</sub>
- 2. a<sub>2</sub>
- 3. a<sub>5</sub>
- 4. cannot be determined
- A1:1
- A2:2
- A3:3
- A4:4

2.0

0.00

11071036	For the train	nenort	ation nr	ohlom								2.0	0.00
	For the transportation problem												
		-			estination								
			D <sub>1</sub>	D <sub>2</sub>	D <sub>3</sub>	D <sub>4</sub>		Supply					
		A	2	11	10	3	7	4					
	Origin	В	1	4	7	2	1	8					
		С	3	9	4	8	12	9					
	Deman	ıd	3	3	4	5	6						
	the initial b	asic fe	easible :	solution	(BFS) b	y N-W c	orner	rule is					
	1. x <sub>11</sub> = 3, 2. x <sub>11</sub> = 1,												
	3. $x_{11} = 3$ ,	x <sub>12</sub> = 1	1, x <sub>22</sub> =	2, x <sub>23</sub> =	2, x <sub>24</sub> =	4, x <sub>34</sub> =	3, x <sub>35</sub>	; = 6					
	4. x <sub>11</sub> = 3,	x <sub>12</sub> = 1	1, x <sub>22</sub> =	2, x <sub>23</sub> =	= 4, x <sub>24</sub> =	2, x <sub>34</sub> =	6, x <sub>35</sub>	; = 3					
	A1:1												
	A2:2												
	A3:3												
	A3:3												
ing Quartien													
	A4 : 4	no garr	no who	50 pay /	off matrix	, ie						2.0	0.00
		he gan	ne who:	se pay-	off matrix	is					1	2.0	0.00
	A4 : 4	he gan	ne who:	se pay-	off matrix	is		Playe	er B			2.0	0.00
	A4 : 4	he gan	ne who:	se pay-	off matrix	ris	1		er B			2.0	0.00
	A4 : 4		ne who:		off matrix	ris			7			2.0	0.00
	A4 : 4				off matrix	ris	1 6					2.0	0.00
	A4 : 4		Player i	A	off matrix	ris			7			2.0	0.00
	A4:4	w two	Player i	A ents:			6		7			2.0	0.00
	Consider the	w two	Player / stateme e optim	A ents: nal strate	egy for A	is (2/5, :	63/5)		7			2.0	0.00
	Consider the Given below Statement Statement In light of the Statement In light of the Given below the Given b	w two (I): Th (II): Th	Player / statem e optim ne optin	A ents: nal strate	egy for A	is (2/5, 3 is (1/3,	6 3/5) 2/3)		7	ie e		2.0	0.00
	Given belo Statement Statement In light of the options given	w two (I): The (II): The he aboren belo	stateme e optim ne optin ove state ow:	ents: nal strate nal strat ements	egy for A legy for E , choose	is (2/5, 3) is (1/3, the mos	6 3/5) 2/3) st appr		7	le e		2.0	0.00
	Given belo Statement In light of thorons given 1. Both State 2. Both State  Consider the state of the state o	w two (I): The he aboren bele temen	stateme optime optimove stateow:  t (I) and t (I) and	ents: nal strate nal strate ements d Stater d Stater	egy for A legy for E , choose nent (II) a nent (II) a	is (2/5, 3 is (1/3, the mos	6 3/5) 2/3) st appr		7	10		2.0	0.00
	Given belo Statement In light of the options given. Both State	w two (I): The he aboren bele temen temen nt (I) is	stateme optime optime ove stateow:  t (I) and t (I) and	ents: nal strate mal strate ements d Stater d Stater ut State	egy for A tegy for E , choose nent (II) a ment (II) a	is (2/5, 3 is (1/3, the mos	6 3/5) 2/3) st appr		7	ne		2.0	0.00
ive Question 11071037	Given belo Statement In light of thooptions given 1. Both Statement 2. Both Statement 3. Statement 3. Statement	w two (I): The he aboren bele temen temen nt (I) is	stateme optime optime ove stateow:  t (I) and t (I) and	ents: nal strate mal strate ements d Stater d Stater ut State	egy for A tegy for E , choose nent (II) a ment (II) a	is (2/5, 3 is (1/3, the mos	6 3/5) 2/3) st appr		7	ne e		2.0	0.00

		A2:2							
		A3:3							
		A4 : 4							
Ohioati	ive Question								
38	11071038							2.0	0.00
		There are 5 jobs, each of order AB. Processing time			he two mach	nines A and	B in the		
				Proc	essing time (h	iours)			
		Job	1	2	3	4	5		
		Machine A	10	2	18	6	20		
		Machine B	4	12	14	16	8		
Objecti	ive Question	The job sequence which of the control of the contro	will minimize t	the elapsed	time is				
39	11071039	A contractor has to supply He finds that, when he stoday. The cost of holding a a production run is Rs. 18 run is  1. 106,000 bearings 2. 104,446 bearings 3. 102,864 bearings 4. 108,244 bearings A1:1  A2:2  A3:3	arts productio a bearing in st	n run, he ca ock for a ye	an produce 2 ear is Rs. 2 a	25,000 bear and the set-	ings per up cost of	2.0	0.00

		A4:4									
Objecti	ve Question									-	I <u></u>
40	11071040	The probability distribution	n of mon	thly sale	s of a ce	rtain item	is as fol	lows:		2.0	0.00
		Monthly sales	0	1	2	3	4	5	6		
		Probability	0.01	0.06	0.25	0.35	0.20	0.03	0.10		
		The cost of carrying inversion shortage is Rs. 70 per more expected cost is  1. 3 2. 4 3. 5 4. 6									
		A1:1 A2:2									
		A3:3 A4:4									
	ve Question										
41	11071041	A TV repairman finds that with mean of 30 minutes the arrival of sets is approday, what is the probabilit 1. 3/5 2. 3/7 3. 3/8 4. 3/10  A1:1  A2:2  A3:3  A4:4	If he rep eximately	airs sets Poisson	in the or with an	der in wh	nich they	come in	, and if	2.0	0.00
Objecti 42	ve Question									2.0	0.00
74	110/1042									2.0	0.00

		Assume time dist	that the inter-ar	rival time exponen	e follows an exp tial with an avera	e at a rate of 30 trains per day. onential distribution and the service age 36 minutes. Then the average		
Object	ive Question							
43	11071043	A projec	t has the followi	na scho	dulo		2.0	0.00
		Aprojec	t nas the following	ing scriet	uule.	1		
		Activity	Time in weeks	Activity	Time in weeks			
		(1,2)	2	(4,5)	3			
		(1,3)	2	(5,9)	5			
		(1,4)	1	(6,8)	1			
		(2,6)	4	(7,8)	4			
		(3,7)	5	(8,9)	3			
		(3,5)	8					
		The dura	ation of the critic	al path	of the project is			
		1. 10 we			/A - A			
		2. 15 we						
		3. 20 we						
		4. 22 we	eks					
		A1:1						
		A2:2						
		A2:2						
		A3:3						
		A4:4						
		2 X F . T						
	ive Question							
44	11071044						2.0	0.00

		Sequence correctly the following steps in PERT/CPM analysis:		
		(A). Identify the critical path		
		(B). Draw the network diagram		
		(C). Establish dependencies across activities		
		(D). Define the activities in the network		
		Choose the <b>correct</b> answer from the options given below:		
		1. (B), (C), (D), (A)		
		2. (A), (B), (D), (C) 3. (C), (B), (D), (A)		
		4. (D), (C), (B), (A)		
		A1:1		
		A2:2		
		A3:3		
		A4:4		
	ive Question			
45	11071045	Consider the NLPP:	2.0	0.00
		Minimize $z = x_1^2 + x_2^2 + x_3^2$ ; subject to $4x_1 + x_2^2 + 2x_3 = 14$ ; $x_1, x_2, x_3 \ge 0$ . The		
		minimum value of z is		
		1. 0.857		
		2. 0.975		
		3. 0.775		
		4. 0.557		
		A1:1		
		A2:2		
		A3:3		
		A4:4		
	ive Question			
46	11071046	When a doctor attends to an emergency case leaving his regular service, it is	2.0	0.00
		called		
		1. reneging		
		2. balking		
		3. pre-emptive queue discipline		
		4. non pre-emptive queue discipline		
		A1:1		
	1		1	1

		A2:2		
		A3:3		
		A4:4		
Object	ive Question			
47	11071047		2.0	0.00
·		In PERT, the span of time between the optimistic and pessimistic time estimates of an activity is		
		1. 3σ		
		2. 6σ		
		3. 9σ		
		4. 12σ		
		A1:1		
		A2:2		
		A3:3		
		A4:4		
Object	ive Question			
48	11071048		2.0	0.00
		Which of the following is not correct?		
		1. When classical method is used in solving a dynamic programming problem,		
		the objective may be linear or non-linear, but the constraints must be non-linear.		
		Dynamic programming deals with the time-dependent decision-making problems.		
		<ul><li>3. LPP can be solved by using dynamic programming approach.</li><li>4. Optimum solution in dynamic programming problem depends on the initial</li></ul>		
		solution.		
		A1:1		
		A2:2		
		A3:3		
		A4:4		
Object	ive Question			
49	11071049		2.0	0.00
		In Beale's method, by increasing the value of any of the non-basic variables, the value of objective function		
		1. can be improved		
		cannot be improved		
		3. can be improved or not		
		4. remains invariant		

$A1:1$ $A2:2$ $A3:3$ $A4:4$ $\hline \begin{array}{c} \hline \hline$		
Objective Question  The quadratic form $\mathbf{x}^T Q \mathbf{x}$ is said to be positive semi-definite, if $ \begin{array}{c c} 1. \mathbf{x}^T Q \mathbf{x} > 0 \\ 2. \mathbf{x}^T Q \mathbf{x} < 0 \\ 3. \mathbf{x}^T Q \mathbf{x} \geq 0 \\ 4. \mathbf{x}^T Q \mathbf{x} \leq 0 \end{array} $ A1: 1  A2: 2		
The quadratic form $\mathbf{x}^T \mathbf{Q} \mathbf{x}$ is said to be positive semi-definite, if  1. $\mathbf{x}^T \mathbf{Q} \mathbf{x} > 0$ 2. $\mathbf{x}^T \mathbf{Q} \mathbf{x} < 0$ 3. $\mathbf{x}^T \mathbf{Q} \mathbf{x} \ge 0$ 4. $\mathbf{x}^T \mathbf{Q} \mathbf{x} \le 0$ A1:1		
The quadratic form $\mathbf{x}^T \mathbf{Q} \mathbf{x}$ is said to be positive semi-definite, if  1. $\mathbf{x}^T \mathbf{Q} \mathbf{x} > 0$ 2. $\mathbf{x}^T \mathbf{Q} \mathbf{x} < 0$ 3. $\mathbf{x}^T \mathbf{Q} \mathbf{x} \geq 0$ 4. $\mathbf{x}^T \mathbf{Q} \mathbf{x} \leq 0$ A1:1	<u>                                     </u>	
1. $\mathbf{x}^{T}Q\mathbf{x} > 0$ 2. $\mathbf{x}^{T}Q\mathbf{x} < 0$ 3. $\mathbf{x}^{T}Q\mathbf{x} \ge 0$ 4. $\mathbf{x}^{T}Q\mathbf{x} \le 0$ A1:1	2.0	0.00
A2:2		
A3:3		
A4:4		